# SiQuENC: Newtonian dynamics for linear motion

#### Neatly and graphically represent **si**tuation(s)

Carefully read the problem three times. Draw object(s) and relevant aspects of environment. Identify requested unknowns.

## Graphically represent <u>qu</u>antities and their relationships Free-body diagram

- **B** Use dashed **b**ubble to indicate object(s) in system.
- **E** Is the Earth nearby (right now)?
- T Is anything touching the system (right now)?
- **A** Draw axes (indicate +x and +y directions), with a positive direction matching direction of system's acceleration. If there is no direction of acceleration, orient axes to minimize the number of forces that fail to point along a drawn axis.

# Identify relevant allowed starting point (in) equation(s) including Newton's laws (stated at bottom row)

	Force	$F_{x}$	$F_{\mathcal{Y}}$		
1					
2					
3					
4					
5					
6					
7	Σ	$ma_x$ (is $a_x = 0$ ?)	$ma_y$ (is $a_y = 0$ ?)		

## Use <u>n</u>umbered steps to show REASoNing

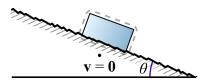
### Communicate

# SiQuENC: Newtonian dynamics for linear motion

**Example:** Complete a force component chart for a block resting on a rough plane inclined at an angle of  $\theta$  above the horizontal.

### Neatly and graphically represent <u>si</u>tuation(s)

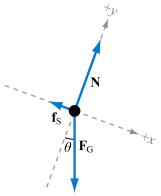
Carefully read the problem three times. Draw object(s) and relevant aspects of environment. Identify requested unknowns.



#### ?: Force component chart

## Graphically represent <u>qu</u>antities and their relationships Free-body diagram

- **B** Use dashed **b**ubble to indicate object(s) in system.
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- **A** Draw axes (indicate +x and +y directions), with a positive direction matching direction of system's acceleration. If there is no direction of acceleration, orient axes to minimize the number of forces that fail to point along a drawn axis.



# Identify relevant allowed starting point (in) equations Including Newton's laws (stated at bottom row)

including Newton's laws (stated at bottom low)					
	Force	$F_{x}$	$F_{\mathcal{Y}}$		
1	$\vec{\mathbf{F}}_{G}$	$+F_{ m G}\sin heta$	$-F_{\mathrm{G}}\cos heta$		
2	$\vec{\mathbf{N}}$	0	+N		
3	$ec{\mathbf{f}}_{\mathrm{S}}$	$-f_{\mathrm{S}}$	0		
4					
5					
6					
7	Σ	$ma_x$ (if $a_x = 0$ ?)	$ma_y$ (if $a_y = 0$ )		

### Use <u>n</u>umbered steps to show REASoNing

#### Communicate